

# HIGH RELIABILITY DC-DC CONVERTER

16-40V Continuous Input 16-50V Transient Input ±5V

Output

5A

88% @ 2.5A / 90% @ 5A

**Total Output** 

**Efficiency** 

Full Power Operation: -55°C to +125°C

The MilQor® series of high-reliability DC-DC converters brings SynQor's field proven high-efficiency synchronous rectifier technology to the Military/Aerospace industry. SynQor's innovative QorSeal® packaging approach ensures survivability in the most hostile environments. Compatible with the industry standard format, these converters operate at a fixed frequency, have no opto-isolators, and follow conservative component derating guidelines. They are designed and manufactured to comply with a wide range of military standards.

### **Design Process**

MQHR series converters are:

- Designed for reliability per NAVSO-P3641-A guidelines
- Designed with components derated per:
  - MIL-HDBK-1547A
  - NAVSO P-3641A

#### **Qualification Process**

MQHR series converters are qualified to:

- MIL-STD-810F
  - consistent with RTCA/D0-160E
- SynQor's First Article Qualification
  - consistent with MIL-STD-883F
- SynQor's Long-Term Storage Survivability Qualification
- SynQor's on-going life test

#### **In-Line Manufacturing Process**

- AS9100 and ISO 9001 certified facility
- Full component traceability
- Temperature cycling
- Constant acceleration
- •24, 96, 160 hour burn-in
- Three level temperature screening





DESIGNED & MANUFACTURED IN THE USA FEATURING QORSEAL® HI-REL ASSEMBLY

#### **Features**

- Fixed switching frequency
- No opto-isolators
- Output over-voltage shutdown
- Clock synchronization
- Primary referenced enable
- Continuous short circuit and overload protection
- Input under-voltage and over-voltage shutdown

### **Specification Compliance**

MQHR series converters (with MQHE filter) are designed to meet:

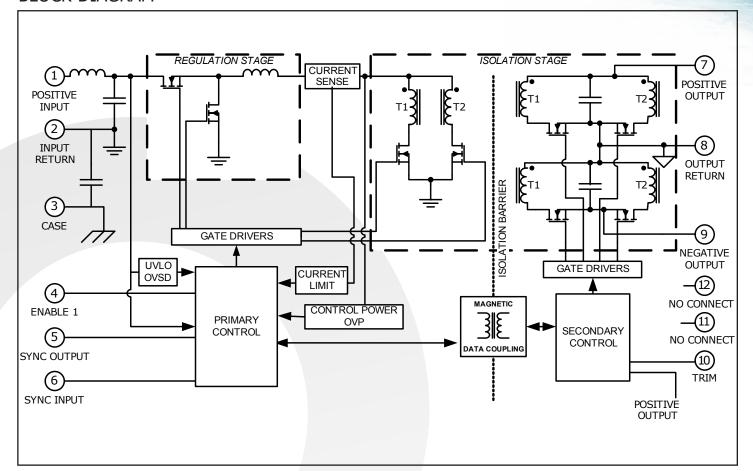
Page 1

- MIL-HDBK-704-8 (A through F)
- RTCA/DO-160 Section 16, 17, 18
- MIL-STD-1275 (B, D) for  $V_{IN} > 16V$
- DEF-STAN 61-5 (part 6)/(5, 6) for V<sub>IN</sub> > 16V
- MIL-STD-461 (C, D, E, F)
- RTCA/DO-160(E, F, G) Section 22

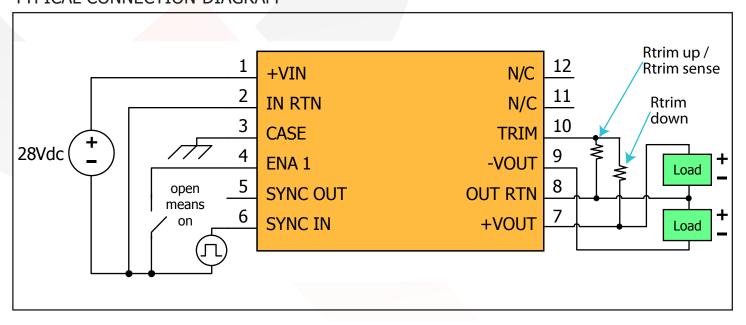


**Current: 5A Total** 

# **BLOCK DIAGRAM**



# TYPICAL CONNECTION DIAGRAM





Output: ±5V

**Current: 5A Total** 

MOHR-28-05D ELECTRICAL CHARACTERISTICS
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MQHR-28-05D ELECTRI	CAL	CHA	KAC	IEK	121172	
Parameter	Min.	Тур.	Max.	Units	Notes & Conditions	Group A
Specifications subject to change without notice					Vin = 28V dc ±5%, +Iout = -Iout = 2.5A, CL = 0µF, free running (see Note 9) unless otherwise specified	Subgroup (see Note 11)
ABSOLUTE MAXIMUM RATINGS						(See Note 11)
Input Voltage						
Non-Operating			60	V		
Operating			60	V	See Note 1	
Reverse Bias (Tcase = 125°C)			-0.8	V		
Reverse Bias (Tcase = -55°C)			-1.2	V		
Isolation Voltage (I/O to case, I to O)	F00		F00	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		
Continuous Transient (≤100µs)	-500 -800		500 800	V		
Operating Case Temperature	-55		125	°C	HB Grade Products, See Notes 2 & 15	
Storage Case Temperature	-65		135	°C	Tib Glade Floducts, See Notes 2 & 13	
Lead Temperature (20s)	05		300	°C		
Voltage at ENA1	-1.2		50	V		
INPUT CHARACTERISTICS	112		30			
Operating Input Voltage Range	16	28	40	V	Continuous	1, 2, 3
, , ,	16	28	50	V	Transient, 1s	, ,
Input Under-Voltage Shutdown					See Note 3	
Turn-On Voltage Threshold	14.75	15.50	16.00	V		1, 2, 3
Turn-Off Voltage Threshold	14.00	14.75	15.50	V		1, 2, 3
Shutdown Voltage Hysteresis	0.65	0.80	1.05	V		
Input Over-Voltage Shutdown					See Note 3	
Turn-Off Voltage Threshold	52.0	55.0	58.0	V		
Turn-On Voltage Threshold	50.5	53.5	56.5	V		
Shutdown Voltage Hysteresis Input Filter Component Values (L\C)	1.0	2.0	3.0	V	Internal Values	
Maximum Input Current		1.0\11.4	2	μΗ\μF	Vin = 16V; +Iout = -Iout = 2.5A	
No Load Input Current (operating)		75	100	MA	VIII = 10V, +10ut = -10ut = 2.5A	1, 2, 3
Disabled Input Current		10	15	mA		1, 2, 3
Input Terminal Current Ripple (pk-pk)		40	75	mA	Bandwidth = 100kHz - 10MHz; see Figure 14	1, 2, 3
OUTPUT CHARACTERISTICS			7.0	11.0	2011.12/0001.19410.21	1/ 1/ 0
Output Voltage Set Point (Tcase = 25°C)					See Note 14	
Positive Ouput	4.95	5.00	5.05	V		1
Negative Output	-5.05	-5.00	-4.95	V		1
Output Voltage Set Point Over Temperature					See Note 14	
Negative Output	-5.08	-5.00	-4.92	V		2, 3 2, 3
Positive Ouput	4.92	5.00	5.08	V	C NI 44	2, 3
Positive Output Voltage Line Regulation	-20	0	20	mV	See Note 14	1, 2, 3
Positive Output Voltage Load Regulation	-20 4.90	5.00	20 5.10	mV V	See Note 14; +Vout @(+Iout=-Iout=0A) - +Vout @(+Iout=-Iout=2.5A) See Note 14	1, 2, 3
Total Positive Output Voltage Range Output Voltage Cross Regulation	75	250	500	mV	See Notes 13 and 14; -Vout @(+Iout=-Iout=1A)Vout @(+Iout=4A, -Iout=1A)	1, 2, 3 1, 2, 3
Output Over-Voltage Shutdown	5.6	6.1	7.1	V	See Notes 13 and 14, -void @(+10dt-1A)void @(+10dt-4A, -10dt-1A)	See Note 5
Output Voltage Ripple and Noise Peak to Peak		15	75	mV	Bandwidth = 10MHz; CL=11µF on both outputs	1, 2, 3
Operating Output Current Range	0	13				
Single Output Operating Current Range			15	ΙΑ	(+Tout) + (-Tout)	l 123
Operating Output Power Range			5 4	A	(+Iout) + (-Iout) Maximum +Iout or -Iout	1, 2, 3
	0		4	A A W	Maximum +Iout or -Iout	1, 2, 3
	0	6.5		Α		1, 2, 3 1, 2, 3
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled	0	6.5 1.6	4 25	A W	Maximum +Iout or -Iout Total on both outputs	1, 2, 3
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled	0		4 25 7.8	A W A A mA	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance	0	1.6	4 25 7.8	A W A A	Maximum +Iout or -Iout Total on both outputs	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS	0	1.6	4 25 7.8	A W A A mA	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient	0 0 5.5	1.6 10	4 25 7.8	Α W A A mA μF	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current	0	1.6 10	4 25 7.8 50 2,500	A W A A mA µF	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current	0 0 5.5	1.6 10	4 25 7.8	Α W A A mA μF	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11µF on both outputs	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient	-300	1.6 10	4 25 7.8 50 2,500	Α W A A mA μF mV	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage	-300 -125	1.6 10	4 25 7.8 50 2,500 300 125	A W A A mA µF mV mV	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11µF on both outputs	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage For a Neg. Step Change in Line Voltage	-300	1.6 10	4 25 7.8 50 2,500	Α W A A mA μF mV	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11µF on both outputs	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage For a Neg. Step Change in Line Voltage Turn-On Transient	-300 -125	1.6 10 -200 200	4 25 7.8 50 2,500 300 125 125	A W A A MA μF mV mV	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11μF on both outputs  Vin step = 16V to 50V; CL=11μF on both outputs; see Note 7	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage For a Neg. Step Change in Line Voltage Turn-On Transient Output Voltage Rise Time	-300 -125	1.6 10 -200 200	4 25 7.8 50 2,500 300 125 125	A W A A MA PIF	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11μF on both outputs  Vin step = 16V to 50V; CL=11μF on both outputs; see Note 7  +Vout = 0.5V to 4.5V; Full Resistive Load	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5 4, 5, 6 4, 5, 6
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage For a Neg. Step Change in Line Voltage Turn-On Transient Output Voltage Rise Time Output Voltage Overshoot	-300 -125	-200 200	4 25 7.8 50 2,500 300 125 125 10 2	A W A A MA PIF	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11µF on both outputs Vin step = 16V to 50V; CL=11µF on both outputs; see Note 7  +Vout = 0.5V to 4.5V; Full Resistive Load Resistive load	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5 4, 5, 6 4, 5, 6 4, 5, 6 See Note 5
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage For a Neg. Step Change in Line Voltage Turn-On Transient Output Voltage Rise Time Output Voltage Overshoot Turn-On Delay, Rising Vin	-300 -125	-200 200 6 0 5.5	300 125 125 10 2 8.0	A W A A MA µF MV MV MV MV MV MV MV MS % MS	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11µF on both outputs Vin step = 16V to 50V; CL=11µF on both outputs; see Note 7  +Vout = 0.5V to 4.5V; Full Resistive Load Resistive load ENA = 5V; see Notes 8 & 10	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5 4, 5, 6 4, 5, 6 4, 5, 6 See Note 5 4, 5, 6
Output DC Current-Limit Inception Back-Drive Current Limit while Enabled Back-Drive Current Limit while Disabled Maximum Output Capacitance DYNAMIC CHARACTERISTICS Output Voltage Deviation Load Transient For a Pos. Step Change in Load Current For a Neg. Step Change in Load Current Output Voltage Deviation Line Transient For a Pos. Step Change in Line Voltage For a Neg. Step Change in Line Voltage Turn-On Transient Output Voltage Rise Time Output Voltage Overshoot	-300 -125	-200 200	4 25 7.8 50 2,500 300 125 125 10 2	A W A A MA PIF	Maximum +Iout or -Iout Total on both outputs See Note 4; +Iout + -Iout; +Iout = -Iout  Total on both outputs  See Note 6 Total Iout step = 2.5A to 5A, 0.5A to 2.5A; CL=11µF on both outputs Vin step = 16V to 50V; CL=11µF on both outputs; see Note 7  +Vout = 0.5V to 4.5V; Full Resistive Load Resistive load	1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 1, 2, 3 See Note 5 4, 5, 6 4, 5, 6 4, 5, 6 See Note 5



Output: ±5V

**Current: 5A Total** 

MOHR-28-05D FLECTRICAL CHARACTERISTICS (Continued)

MUNK-28-USD ELECTRI	.CAL	CHAI	KAC	I EKT:	STICS (Continued)	
Parameter	Min.	Тур.	Max.	Units	Notes & Conditions Vin = 28V dc ±5%, +Iout = -Iout = 2.5A, CL = 0μF,	Group A Subgroup
Specifications subject to change without notice					free running (see Note 9) unless otherwise specified	(see Note 11)
EFFICIENCY						
Iout = 5 A (16 Vin)		90		%		
Iout = 2.5 A (16 Vin)		89		%		
Iout = 5 A (28 Vin)	86	90		%		1, 2, 3
Iout = 2.5 A (28 Vin)		88		%		
Iout = 5 A (40 Vin)		89		%		
Iout = 2.5 A (40 Vin)		87		%		
Iout = 5 A (50 Vin)		88		%		
Load Fault Power Dissipation		2.5		W	Sustained short circuit on output	
ISOLATION CHARACTERISTICS						
Isolation Voltage					Dielectric strength	
Input RTN to Output RTN	500			V		1
Any Input Pin to Case	500			V		1
Any Output Pin to Case	500			V		1
Isolation Resistance (in rtn to out rtn)	100			MΩ		1
Isolation Resistance (any pin to case)	100			MΩ		1
Isolation Capacitance (in rtn to out rtn)		22		nF		1
FEATURE CHARACTERISTICS						
Switching Frequency (free running)	500	550	600	kHz		1, 2, 3
Synchronization Input						
Frequency Range	500		700	kHz		1, 2, 3
Logic Level High	2.0		5.5	V		1, 2, 3
Logic Level Low	-0.5		0.8	V		1, 2, 3
Duty Cycle	20		80	%		See Note 5
Synchronization Output						
Pull Down Current	20			mA	VSYNC OUT = 0.8V	See Note 5
Duty Cycle	40		60	%	Output connected to SYNC IN of other MQHR unit	See Note 5
Enable Control (ENA)						
Off-State Voltage			0.8	V		1, 2, 3
Module Off Pulldown Current	80			μA	Current drain required to ensure module is off	See Note 5
On-State Voltage	2			V		1, 2, 3
Module On Pin Leakage Current			20	μA	Imax draw from pin allowed with module still on	See Note 5
Pull-Up Voltage	3.2	4.0	4.8	·V	See Figure A	
Output Voltage Trim Range	-10		10	%	See Figure E	1, 2, 3
RELIABILITY CHARACTERISTICS						
Calculated MTBF (MIL-STD-217F2)						
GB @ Tcase = 70°C		4030		103 Hrs.		
AIF @ Tcase = 70°C		338		103 Hrs.		
WEIGHT CHARACTERISTICS						
Device Weight		45		g		
		•			1	

#### **Electrical Characteristics Notes**

- 1. Converter will undergo input over-voltage shutdown.
- 2. Derate output power to 50% of rated power at Tcase = 135°C. 135°C is above the specified operating range. See Figure 11.
- 3. High or low state of input voltage must persist for about 200µs to be acted on by the shutdown circuitry.
- 4. Current limit inception is defined as the point where the output voltage has dropped to 90% of its nominal value.
- 5. Parameter not tested but guaranteed to the limit specified.
- 6. Load current transition time  $\geq 10 \mu s$ .
- 7. Line voltage transition time  $\geq 100 \mu s$ .
- 8. Input voltage rise time ≤ 250µs.
- 9. Operating the converter at a synchronization frequency above the free running frequency will cause the converter's efficiency to be slightly reduced and it may also cause a slight reduction in the maximum output current/power available. For more information consult the factory.
- 10. After a disable or fault event, module is inhibited from restarting for 100ms. See Shut Down section of the Control Features description.

  11. Only the ES and HB grade products are tested at three temperatures. The C grade products are tested at one temperature. Please refer to the Construction and Environmental Stress Screening Options table for details.
- 12. These derating curves apply for the ES and HB grade products. The C grade product has a maximum case temperature of 70°C.
- 13. The regulation stage operates to control the positive output. The negative output displays the cross regulation.
- 14. All +Vout and -Vout voltage measurements are made with Kelvin probes on the output leads.
- 15. The specified operating case temperature for ES grade products is -45°C to 100°C. The specified operating case temperature for C grade products is 0°C to 70°C.

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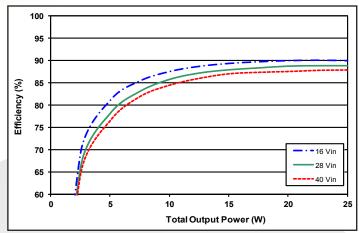
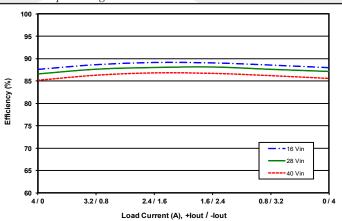


Figure 1: Efficiency vs. output power, from zero load to full load with equal load on the +5V and -5V outputs at minimum, nominal, and maximum input voltage at Tcase=25°C.



**Figure 3**: Efficiency vs. output power, with total output current fixed at 80% load (20W) and loads split as shown between the +5V and -5V outputs at minimum, nominal, and maximum input voltage at Tcase=25°C.

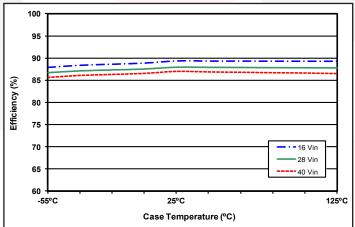


Figure 5: Efficiency at 60% load (1.5A load on +5V and 1.5A load on -5V) versus case temperature for Vin = 16V, 28V and 40V.

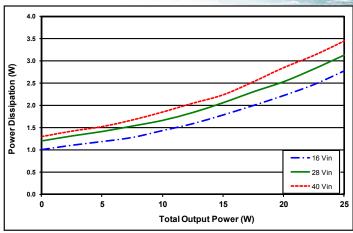


Figure 2: Power dissipation vs. output power, from zero load to full load with equal load on the +5V and -5V outputs at minimum, nominal, and maximum input voltage at Tcase=25°C.

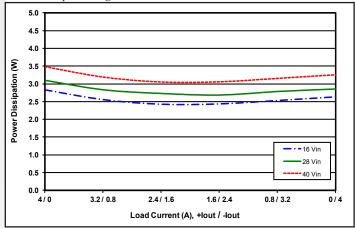
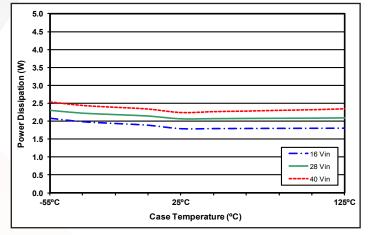
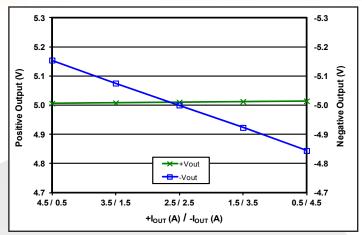


Figure 4: Power dissipation vs. output power, with total output current fixed at 80% load (20W) and loads split as shown between the +5V and -5V outputs at minimum, nominal, and maximum input voltage at Tcase=25°C.



**Figure 6**: Power Dissipation at 60% load (1.5A load on +5V and 1.5A load on -5V) versus case temperature for Vin = 16V, 28V and 40V.





**Figure 7**: Load regulation vs. load current with power fixed at full load (25W) and load currents split as shown between the +5V and -5V outputs, at niminal input voltage and Tcase  $=25^{\circ}$ C.

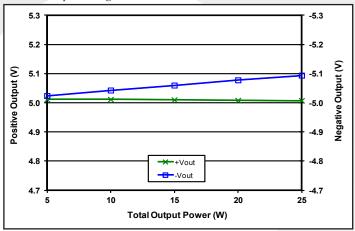


Figure 9: Load regulation vs. total output power from zero to full load where +Iout equals three times -Iout a nominal input voltage and Tcase = 25°C.

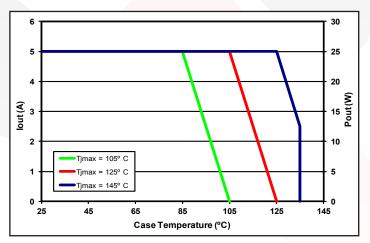


Figure 11: Output Current / Output Power derating curve as a function of Tcase and the Maximum desired power MOSFET junction temperature at Vin = 28V (see Note 12).

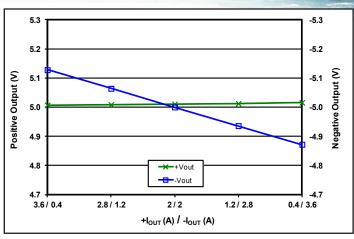
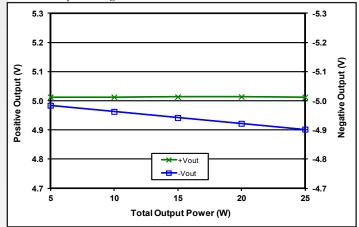


Figure 8: Load regulation vs. load current with power fixed at 80% load (20W) and load currents split as shown between the +5V and -5V outputs, at niminal input voltage and Tcase = 25°C.



**Figure 10**: Load regulation vs. total output power from zero to full load where -Iout equals three times +Iout a nominal input voltage and Tcase = 25°C.

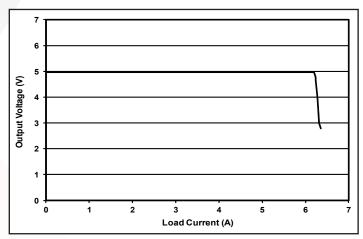


Figure 12: Positive output voltage vs. total load current, evenly split, showing typical current limit curves at Vin = 28V.



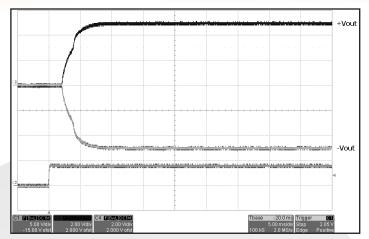


Figure 13: Turn-on transient at full load current (resistive load) (5 ms/div). Input voltage pre-applied. Ch 1: ENA1 (5V/div); Ch 2: +Vout (2V/div); Ch 3: -Vout (2V/div).

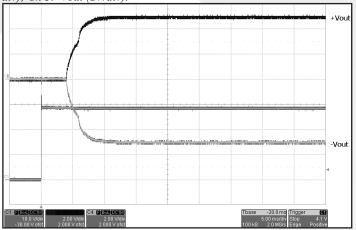


Figure 15: Turn-on transient at full load current, after application of input voltage (ENA 1 logic high) (5ms/div). Input voltage pre-applied. Ch 1: Vin (10V/div); Ch 2: +Vout (2V/div); Ch 3: -Vout (2V/div).

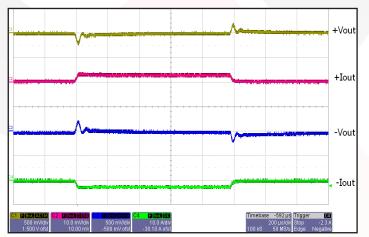


Figure 17: Output voltage response to step-change in total load current (0%-50%-0%) of total lout (max) split 50%/50%. Load cap:  $1\mu F$  ceramic cap and  $10\mu F$ ,  $100m\Omega$  ESR tantalum cap. Ch 1: +Vout (500mV/div); Ch 2: +Iout (5A/div); Ch 3: -Vout (500mV/div); Ch 4: -Iout (5A/div).

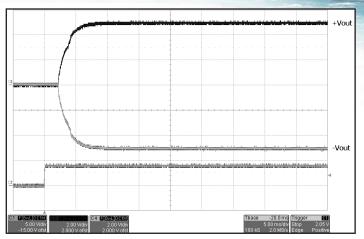


Figure 14: Turn-on transient at zero load current (5ms/div). Input voltage pre-applied. Ch 1: ENA1 (5V/div); Ch 2: +Vout (2V/div); Ch 3:

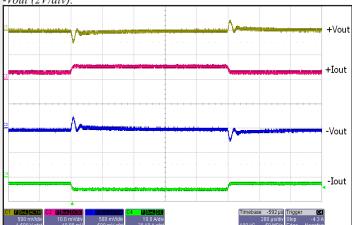


Figure 16: Output voltage response to step-change in total load current (50%-100%-50%) of total lout (max) split 50%/50%. Load cap:  $1\mu$ F ceramic cap and  $10\mu$ F,  $100m\Omega$  ESR tantalum cap. Ch 1: +Vout (500mV/div); Ch 2: +Iout (5A/div); Ch 3: -Vout (500mV/div); Ch 4: -Iout (5A/div).

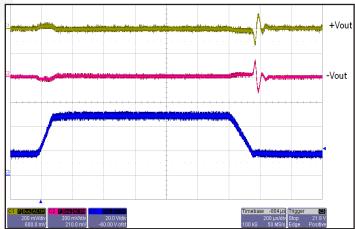


Figure 18: Output voltage response to step-change in input voltage (16V-50V-16V). Load cap:  $1\mu F$  ceramic cap and  $10\mu F$ ,  $100m\Omega$  ESR tantalum cap. Ch 1: +Vout (200mV/div); Ch 2: -Vout (200mV/div); Ch 4: Vin (20V/div).

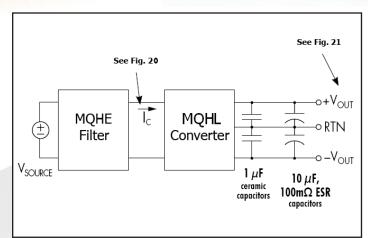
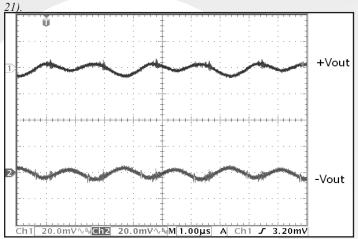
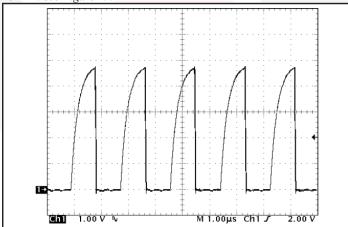


Figure 19: Test set-up diagram showing measurement points for Input Terminal Ripple Current (Figure 20) and Output Voltage Ripple (Figure



**Figure 21**: Output voltage ripple, +Vout (Ch 1) and -Vout (Ch 2), at nominal input voltage and full load current evenly split (20mV/div). Load capacitance: 1μF ceramic cap and 10μF tantalum cap.. Bandwidth; 10MHz. See Figure 19.



**Figure 23**: SYNC OUT vs. time, driving SYNC IN of a second SynQor MQHL converter.

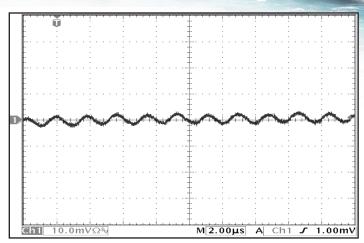
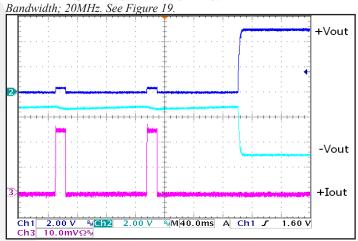
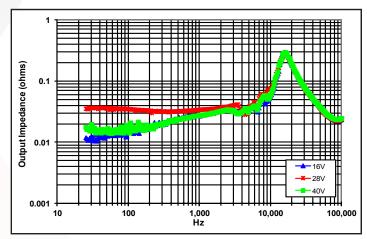


Figure 20: Input terminal current ripple, ic, at full rated output current and nominal input voltage with SynQor MQ filter module (50mA/div).



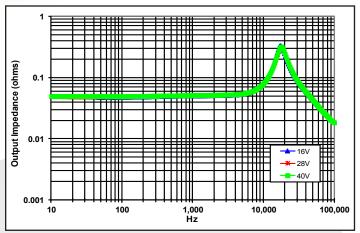
**Figure 22**: Rise of output voltage after the removal of a short across the positive output terminals. Ch l: +Vout (2V/div); Ch 2: -Vout (2V/div); Ch 3:+Iout (2.5A/div).



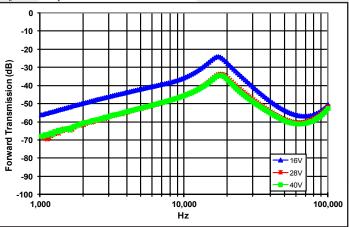
**Figure 24**: Magnitude of incremental output impedance of +5V output (+Zout =+ vout/+iout) for minimum, nominal, and maximum input voltage at full rated power.



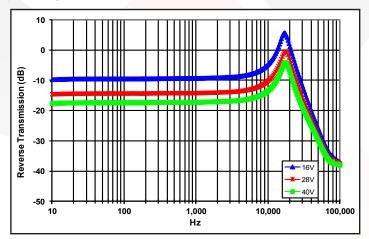
Output: ±5V



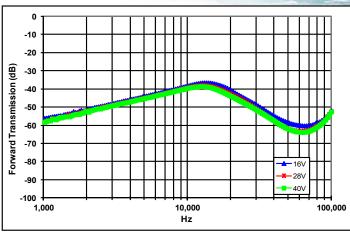
**Figure 25**: Magnitude of incremental output impedance of -5V output (-Zout = -vout/-iout) for minimum, nominal, and maximum input voltage at full rated power.



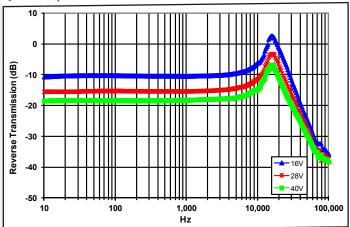
**Figure 27**: Magnitude of incremental forward transmission of -5V output (-FT = -vout/-vin) for minimum, nominal, and maximum input voltage at full rated power.



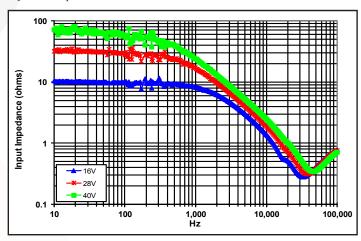
**Figure 29**: Magnitude of incremental reverse transmission of -5V output (-RT = -iin/-iout) for minimum, nominal, and maximum input voltage at full rated power.



**Figure 26**: Magnitude of incremental forward transmission of +5V output (+FT = +vout/+vin) for minimum, nominal, and maximum input voltage at full rated power.



**Figure 28**: Magnitude of incremental reverse transmission of +5V output (+RT = +iin/+iout) for minimum, nominal, and maximum input voltage at full rated power.



**Figure 30**: Magnitude of incremental input impedance (Zin = vin/iin) for minimum, nominal, and maximum input voltage at full rated power.

**Current: 5A Total** 

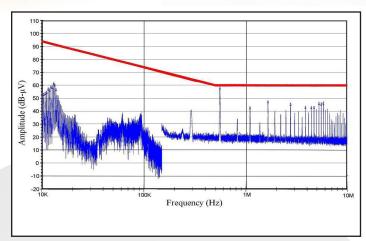


Figure 31: High frequency conducted emissions of standalone MQHL-28-05S, 5Vout module at 50W output, as measured with Method CE102. Limit line shown is the 'Basic Curve' for all applications with a 28V source.

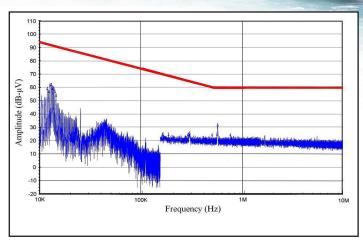


Figure 32: High frequency conducted emissions of MQHL-28-05S, 5Vout module at 50W output with MQHE-28-P filter, as measured with Method CE102. Limit line shown is the 'Basic Curve' for all applications with a 28V source.

**Current: 5A Total** 

### BASIC OPERATION AND FEATURES

The MQHR DC/DC converter uses a two-stage power conversion topology. The first, or regulation, stage is a buck-converter that keeps the output voltage constant over variations in line, load, and temperature. The second, or isolation, stage uses transformers to provide the functions of input/output isolation and voltage transformation to achieve the output voltage required.

In the dual output converter there are two secondary windings in the transformer of the isolation stage, one for each output. There is only one regulation stage, however, and it is used to control the positive output. The negative output therefore displays "Cross-Regulation", meaning that its output voltage depends on how much current is drawn from each output.

Both the positive and the negative outputs share a common OUTPUT RETURN pin.

Both the regulation and the isolation stages switch at a fixed frequency for predictable EMI performance. The isolation stage switches at one half the frequency of the regulation stage, but due to the push-pull nature of this stage it creates a ripple at double its switching frequency. As a result, both the input and the output of the converter have a fundamental ripple frequency of about 550 kHz in the free-running mode.

Rectification of the isolation stage's output is accomplished with synchronous rectifiers. These devices, which are MOSFETs with a very low resistance, dissipate far less energy than would Schottky diodes. This is the primary reason why the MQHR converters have such high efficiency, particularly at low output voltages.

Besides improving efficiency, the synchronous rectifiers permit operation down to zero load current. There is no longer a need for a minimum load, as is typical for converters that use diodes for rectification. The synchronous rectifiers actually permit a negative load current to flow back into the converter's output terminals if the load is a source of short or long term energy. The MQHR converters employ a "backdrive current limit" to keep this negative output terminal current small.

There is a control circuit in the MQHR converter that determines the conduction state of the power switches. It communicates across the isolation barrier through a magnetically coupled device. No opto-isolators are used.

An input under-voltage shutdown feature with hysteresis is provided, as well as an input over-voltage shutdown and an

output over-voltage limit. There is also an output current limit that is nearly constant as the load impedance decreases (i.e., there is not fold-back or fold-forward characteristic to the output current under this condition). When a load fault is removed, the output voltage rises exponentially to its nominal value without an overshoot. If a load fault pulls the output voltage below about 60% of nominal, the converter will shut down to attempt to clear the load fault. After a short delay it will try to auto-restart.

The MQHR converter's control circuit does not implement an over-temperature shutdown.

The following sections describe the use and operation of additional control features provided by the MQHR converter.

### **CONTROL FEATURES**

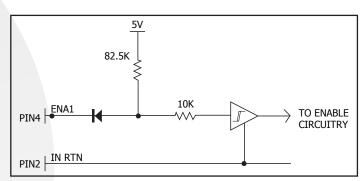


Figure A: Circuit diagram shown for reference only, actual circuit components may differ from values shown for equivalent circuit.

**ENABLE:** The MQHR converter has one enable pin, ENA1 (pin 4), which is referenced with respect to the converter's input return (pin 2). It must have a logic high level for the converter to be enabled; a logic low inhibits the converter.

The enable pin is internally pulled high so that an open connection will enable the converter. Figure A shows the equivalent circuit looking into the enable pin. It is TTL compatible and has hysteresis.

**SHUT DOWN:** The MQHR converter will shut down in response to only five conditions: ENA input low, VIN input below under-voltage shutdown threshold, VIN input above over-voltage shutdown threshold, output voltage below the output under-voltage threshold, and output voltage above the output over-voltage threshold. Following any shutdown event, there is a startup inhibit delay which will prevent the converter from restarting for approximately 100ms. After the 100ms delay elapses, if the enable inputs are high and the input voltage is within the operating range, the converter

**Current: 5A Total** 

will restart. If the VIN input is brought down to nearly 0V and back into the operating range, there is no startup inhibit, and the output voltage will rise according to the "Turn-On Delay, Rising Vin" specification.

**SYNCHRONIZATION:** The MQHR converter's switching frequency can be synchronized to an external frequency source that is in the 500 kHz to 700 kHz range. A pulse train at the desired frequency should be applied to the SYNC IN pin (pin 6) with respect to the INPUT RETURN (pin 2). This pulse train should have a duty cycle in the 20% to 80% range. Its low value should be below 0.8V to be guaranteed to be interpreted as a logic low, and its high value should be above 2.0V to be guaranteed to be interpreted as a logic high. The transition time between the two states should be less than 300ns.

If the MQHR converter is not to be synchronized, the SYNC IN pin should be left open circuit. The converter will then operate in its free-running mode at a frequency of approximately 550 kHz.

If, due to a fault, the SYNC IN pin is held in either a logic low or logic high state continuously, or the SYNC IN frequency is outside the 500-700 kHz range, the MQHR converter will revert to its free-running frequency.

The MQHR converter also has a SYNC OUT pin (pin 5). This output can be used to drive the SYNC IN pins of as many as ten (10) other MQHR converters. The pulse train coming out of SYNC OUT has a duty cycle of 50% and a frequency that matches the switching frequency of the converter with which it is associated. This frequency is either the free-running frequency if there is no valid synchronization signal at the SYNC IN pin, or the synchronization frequency if there is.

The synchronization feature is entirely compatible with that of SynQor's MQFL family of converters.

Figure B shows the equivalent circuit looking into the SYNC IN pin and Figure C shows the equivalent circuit looking into the SYNC OUT pin.

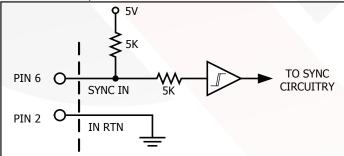


Figure B: Equivalent circuit looking into the SYNC IN pin with respect to the IN RTN (input return) pin.

**OUTPUT VOLTAGE TRIM:** If desired, it is possible to increase or decrease the MQHR dual converter's output voltage from its nominal value. To increase the output voltage a resistor, Rtrim up, should be connected between TRIM pin (pin 10) and the OUTPUT RETURN pin (pin 8), as shown in Figure D. The value of this resistor should be determined according to the following equation of from Figure E:

Rtrim up(
$$\Omega$$
) =  $\frac{6000\Omega*Vnom}{Vout - Vnom}$  -  $30000\Omega$ 

where:

Vnom = the converter's nominal output voltage, Vout = the desired output voltage (greater than Vnom), and Rtrim up is in Ohms.

As the output voltage is trimmed up, it produces a greater voltage stress on the converter's internal components and may cause the converter to fail to deliver the desired output voltage at the low end of the input voltage range at the higher end of the load current and temperature range. Please consult the factory for details. To trim the output voltage below its nominal value, connect an external resistor between the TRIM pin and the POSITIVE OUTPUT pin (pin 7), as shown in Figure D. The value of this trim down resistor should be chosen according to the following equation or from Figure E:

Rtrim down(
$$\Omega$$
) =  $\frac{15100\Omega*Vout - 6000\Omega*Vnom}{Vnom - Vout}$  -  $30000\Omega$ 

where:

Vnom = the converter's nominal output voltage,
Vout = the desired output voltage (less than Vnom),
and
Rtrim down is in Ohms.

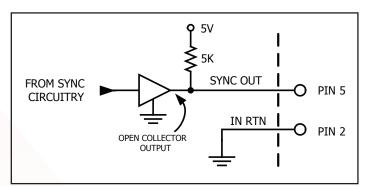


Figure C: Equivalent circuit looking into SYNC OUT pin with respect to the IN RTN (input return) pin.

**Current: 5A Total** 

**INPUT UNDER-VOLTAGE SHUTDOWN:** The MQHR converter has an under-voltage shutdown feature that ensures the converter will be off if the input voltage is too low. The input voltage turn-on threshold is higher than the turn-off threshold. In addition, the MQHR converter will not respond to a state of the input voltage unless it has remained in that state for more than about 200µs. This hysteresis and the delay ensure proper operation when the source impedance is high or in a noisy environment.

**INPUT OVER-VOLTAGE SHUTDOWN:** The MQHR converter also has an over-voltage feature that ensures the converter will be off if the input voltage is too high. It also has a hysteresis and time delay to ensure proper operation.

**OUTPUT OVER-VOLTAGE SHUTDOWN:** The MQHR converter will shut down if the voltage at its power output pins ever exceeds about 130% of the nominal value. The shutdown threshold does not change with output trim or sense drops; excessive trim-up or output wiring drops may cause an output over-voltage shutdown event. After a startup inhibit delay, the converter will attempt to restart.

**OUTPUT UNDER-VOLTAGE SHUTDOWN:** The MQHR converter will also shut down if the voltage at its power output pins ever dips below 60% of the nominal value for more than a few milliseconds. Output voltage reduction due to output current overload (current limit) is the most common trigger for this shutdown. The shutdown threshold does not change with output trim but at only 10%, trimdown should not trigger this event. After a startup inhibit delay, the converter will attempt to restart. This shutdown is disabled during startup.

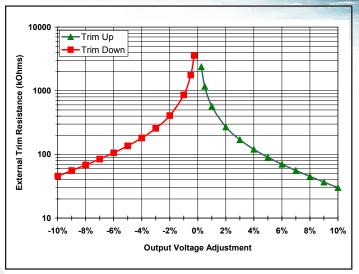
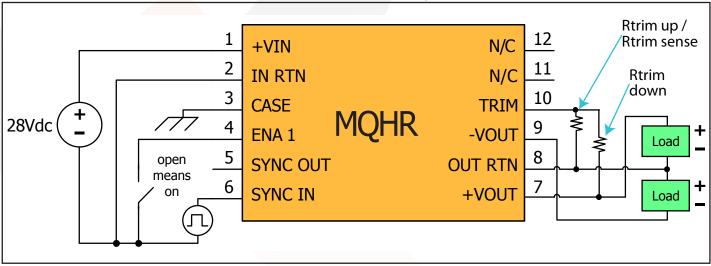


Figure E: Trim up and Trim down as a function of external trim resistance.

**BACK-DRIVE CURRENT LIMIT:** Converters that use MOSFETs as synchronous rectifiers are capable of drawing a negative current from the load if the load is a source of short- or long-term energy. This negative current is referred to as a "back-drive current".

Conditions where back-drive current might occur include paralleled converters that do not employ current sharing. It can also occur when converters having different output voltages are connected together through either explicit or parasitic diodes that, while normally off, become conductive during startup or shutdown. Finally, some loads, such as motors, can return energy to their power rail. Even a load capacitor is a source of back-drive energy for some period of time during a shutdown transient.



*Figure D: Typical connection for output voltage trimming.* 

Output: ±5V

**Current: 5A Total** 

To avoid any problems that might arise due to back-drive current, the MQHR converters limit the negative current that the converter can draw from its output terminals. The threshold for this back-drive current limit is placed sufficiently below zero so that the converter may operate properly down to zero load, but its absolute value (see the Electrical Characteristics page) is small compared to the converter's rated output current.

**CURRENT LIMIT:** In the event of excess load, the MQHR converter will quickly reduce its output voltage to keep the load current within safe limits (see Figure 12). If the overload persists for more than 14 milliseconds, the converter will shut off, wait a restart delay, and then automatically attempt to re-start. The timeout is internally implemented with an integrator: counting up whenever current limit is active, and counting down at 1/5th the rate whenever current limit becomes inactive. In this way a series of short-duration overloads will not cause the converter to shut down, while it will shut down in response to sustained overloads.

**THERMAL CONSIDERATIONS:** Figure 11 shows the suggested Power Derating Curves for this converter as a function of the case temperature and the maximum desired power MOSFET junction temperature. All other components within the converter are cooler than its hottest MOSFET, which at full power is no more than 20°C higher than the case temperature directly below this MOSFET.

The Mil-HDBK-1547A component derating guideline calls for a maximum component temperature of 105°C. Figure 11 therefore has one power derating curve that ensures this limit is maintained. It has been SynQor's extensive experience that reliable long-term converter operation can be achieved with a maximum component temperature of 125°C. In extreme cases, a maximum temperature of 145°C is permissible, but not recommended for long-term operation where high reliability is required. Derating curves for these higher temperature limits are also included in Figure 11. The maximum case temperature at which the converter should be operated is 135°C.

When the converter is mounted on a metal plate, the plate will help to make the converter's case bottom a uniform temperature. How well it does so depends on the thickness of the plate and on the thermal conductance of the interface layer (e.g. thermal grease, thermal pad, etc.) between the case and the plate. Unless this is done very well, it is important not to mistake the plate's temperature for the maximum case temperature. It is easy for them to be as much as 5-10°C different at full power and at high temperatures. It is suggested that a thermocouple be attached directly to the converter's case through a small hole in the plate when investigating how hot the converter is getting. Care must also be made to ensure that there is not a large thermal resistance between the thermocouple and the case due to whatever adhesive might be used to hold the thermocouple in place.

**INPUT SYSTEM INSTABILITY:** This condition can occur because any dc-dc converter appears incrementally as a negative resistance load. A detailed application note titled "Input System Instability" is available on the SynQor website which provides an understanding of why this instability arises, and shows the preferred solution for correcting it.

Output: ±5V

**Current: 5A Total** 

#### CONSTRUCTION AND ENVIRONMENTAL STRESS SCREENING OPTIONS

	Screening	Consistent with MIL-STD-883F	C-Grade ( specified from 0 °C to +70 °C	ES-Grade  ( specified from  -45 °C to +100 °C )	HB-Grade ( specified from (-55 °C to +125 °C )
	Element Evaluation		No	Yes	Yes
	Internal Visual	*	Yes	Yes	Yes
	Temperature Cycle	Method 1010	No	Condition B (-55 °C to +125 °C)	Condition C (-65 °C to +150 °C)
C	onstant Acceleration	Method 2001 (Y1 Direction)	No	500g	Condition A (5000g)
	Burn-in	Method 1015	24 Hrs @ +125 °C	96 Hrs @ +125 °C	160 Hrs @ +125 °C
	Final Electrical Test	Method 5005 (Group A)	+25 °C	-45, +25, +100 °C	-55, +25, +125 °C
	Mechanical Seal, Thermal, and Coating Process			Full QorSeal	Full QorSeal
	External Visual	2009	*	Yes	Yes
C	Construction Process			QorSeal	QorSeal

#### \* Per IPC-A-610 Class 3

MilQor® Hi-Rel converters and filters are offered in three variations of environmental stress screening options. All ES-Grade and HB-Grade MilQor Hi-Rel converters use SynQor's proprietary QorSeal® Hi-Rel assembly process that includes a Parylene-C coating of the circuit, a high performance thermal compound filler, and a nickel barrier gold plated aluminum case. Each successively higher grade has more stringent mechanical and electrical testing, as well as a longer burn-in cycle. The ES- and HB-Grades are also constructed of components that have been procured through an element evaluation process that pre-qualifies each new batch of devices.

Output: ±5V

**Current: 5A Total** 

### **MIL-STD-810F Qualification Testing**

MIL-STD-810F Test	Method	Description Description
Fungus	508.5	Table 508.5-I
Altitude	500.4 - Procedure I	Storage: 70,000 ft / 2 hr duration
Attitude	500.4 - Procedure II	Operating: 70,000 ft / 2 hr duration; Ambient Temperature
Rapid Decompression	500.4 - Procedure III	Storage: 8,000 ft to 40,000 ft
Acceleration	513.5 - Procedure II	Operating: 15 g
Salt Fog	509.4	Storage
High Townserstone	501.4 - Procedure I	Storage: 135°C / 3 hrs
High Temperature	501.4 - Procedure II	Operating: 100°C / 3 hrs
Low Temperature	502.4 - Procedure I	Storage: -65°C / 4 hrs
502.4 - Procedure		Operating: -55°C / 3 hrs
Temperature Shock	503.4 - Procedure I - C	Storage: -65°C to 135°C; 12 cycles
Rain	506.4 - Procedure I	Wind Blown Rain
Immersion	512.4 - Procedure I	Non-Operating
Humidity	507.4 - Procedure II	Aggravated cycle @ 95% RH (Figure 507.5-7 aggravated temp - humidity cycle, 15 cycles)
Random Vibration	5 <mark>14.5 -</mark> Procedure I	10 - 2000 Hz, PSD level of 1.5 g <sup>2</sup> /Hz (54.6 grms), duration = 1 hr/axis
Shock	516.5 - Procedure I	20 g peak, 11 ms, Functional Shock (Operating no load) (saw tooth)
Shock	516.5 - Procedure VI	Bench Handling Shock
Sinusoidal vibration	514.5 - Category 14	Rotary wing aircraft - helicopter, 4 hrs/axis, 20 g (sine sweep from 10 - 500 Hz)
Cond and Door	510.4 - Procedure I	Blowing Dust
Sand and Dust	510.4 - Procedure II	Blowing Sand

Output: ±5V

**Current: 5A Total** 

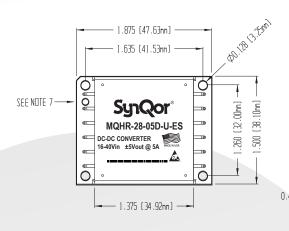
### First Article Testing consistent with MIL-STD-883F

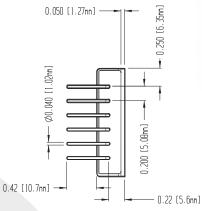
First Article Testing consistent with MIL-STD-883F									
MIL-STD-883F Test	Method	Description							
Electrical Tests	5005								
Physical Dimensions test	2016								
Resistance to Solvents test	2015.13								
Solderability test	2003.8								
Lead Integrity test	2004.5								
Salt Atmosphere test	1009.8	Condition "A"							
Adhesion of Lead Finish test	2025.4								
Altitude Operation test	1001	Condition "C"							
ESD Sensitivity	3015.7	Class 2							
Stabilization Bake test	1008.2	Condition "C"							
Vibration Fatigue test	2005.2	Condition "A"							
Random Vibration test	2026	Condition "II K"							
Sequential Test Group #1									
Life Test – Steady State test	1005.8								
Life Test – Intermittent Duty test	1006								
Sequential Test Group #2									
Temperature Cycle test	1010.8	Condition "C"							
Constant Acceleration test	2001.2	Condition "A"							
Sequential Test Group #3									
Thermal Shock test	1011.9	Condition "B"							
Temperature Cycle test	1010.8	Condition "C"							
Moisture Resistance test	1004.7	With Sub cycle							
Sequential Test Group #4									
Mechanical Shock test	2002.4	Condition "B"							
Variable Frequency Vibration test	2007.3	Condition "A"							

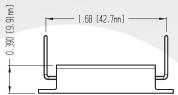


Output: ±5V

**Current: 5A Total** 



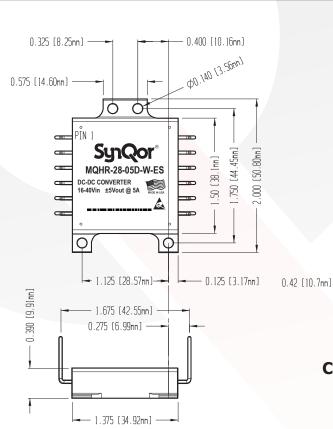


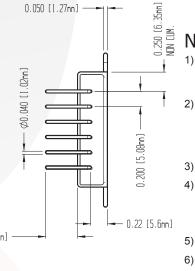


Case U

### PIN DESIGNATIONS

Pin #	Function
1	Positive input
2	Input return
3	Case
4	Enable 1
5	Sync output
6	Sync input
7	Positive output
8	Output return
9	Negative output
10	Trim
11	No connection
12	No connection





Case W

### **NOTES**

- Case: Aluminum with gold over nickel plate finish for the C, ES, and HB Grade products.
- ) Pins: Diameter: 0.040" (1.02mm) Material: Copper
  - Finish: Copper alloy with Gold over Nickel plating, followed by Sn/Pb solder dip
  - All dimensions in inches (mm)
- 4) Tolerances: a) x.xx +/-0.02 in. (x.x +/-0.5mm)
  - b) x.xxx +/-0.010 in. (x.xx +/-0.25mm)
- 5) Weight: 1.6 oz (45.4 g) typical
- 6) Workmanship: Meets or exceeds IPC-A-610 Class III
- 7) Pin 1 identification hole, not intended for mounting
- 8) Baseplate flatness tolerance is 0.004" (.10mm) TIR for surface

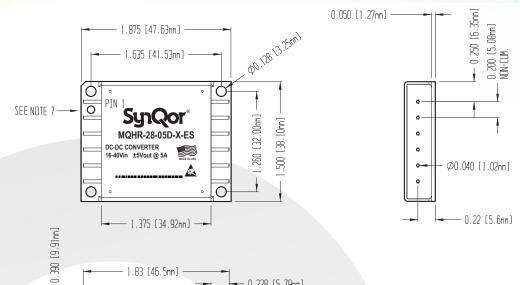


1.83 [46.5mm]

**MQHR-28-05D** 

Output: ±5V

**Current: 5A Total** 

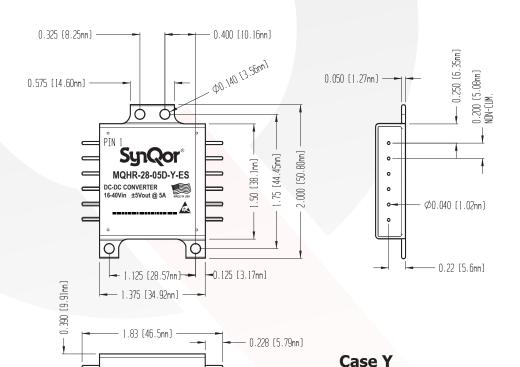


0.228 [5.79mm]

Case X

### PIN DESIGNATIONS

Pin #	Function
1	Positive input
2	Input return
3	Case
4	Enable 1
5	Sync output
6	Sync input
7	Positive output
8	Output return
9	Negative output
10	Trim
11	No connection
12	No connection



### **NOTES**

4)

- Case: Aluminum with gold over nickel plate finish for the C, ES, and HB Grade products.
- Diameter: 0.040" (1.02mm) 2) Pins: Material: Copper

Finish: Copper alloy with Gold over Nickel plating, followed by Sn/Pb solder dip

- 3) All dimensions in inches (mm)
  - a) x.xx + /-0.02 in. Tolerances: (x.x + /-0.5mm)b) x.xxx + /-0.010 in.

(x.xx + /-0.25mm)

- 5) Weight: 1.6 oz (45.4 g) typical
- 6) Workmanship: Meets or exceeds IPC-A-610 Class III
- 7) Pin 1 identification hole, not intended for mounting
- Baseplate flatness tolerance is 0.004" (.10mm) TIR for surface



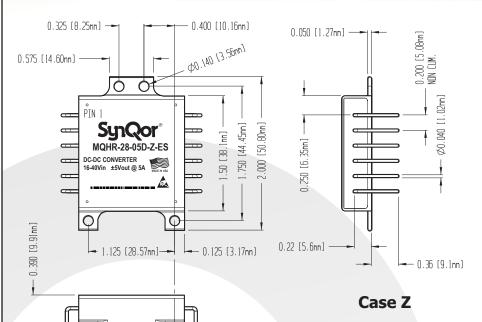
0.28 [7.1mm] - 1.375 [34.92mm]

1.68 [42.7nn]

MQHR-28-05D

Output: ±5V

**Current: 5A Total** 



### PIN DESIGNATIONS

Pin #	Function
1	Positive input
2	Input return
3	Case
4	Enable 1
5	Sync output
6	Sync input
7	Positive output
8	Output return
9	Negative output
10	Trim
11	No connection
12	No connection

### **NOTES**

- 1) Case: Aluminum with gold over nickel plate finish for the C,
  - ES, and HB Grade products.
- 2) Pins: Diameter: 0.040" (1.02mm)
  - Material: Copper
  - Finish: Copper alloy with Gold over Nickel plating, followed by Sn/Pb solder dip
- 3) All dimensions in inches (mm)
- 4) Tolerances: a) x.xx +/-0.02 in.
  - (x.x +/-0.5mm) b) x.xxx +/-0.010 in. (x.xx +/-0.25mm)
    - (XIXX 1) 012311
- 5) Weight: 1.6 oz (45.4 g) typical
  - 6) Workmanship: Meets or exceeds IPC-A-610 Class III
- 7) Pin 1 identification hole, not intended for mounting
- 8) Baseplate flatness tolerance is 0.004" (.10mm) TIR for surface

Output: ±5V

**Current: 5A Total** 

# **MilQor Converter FAMILY MATRIX**

The tables below show the array of MilQor converters available. When ordering SynQor converters, please ensure that you use the complete part number according to the table in the last page. Contact the factory for other requirements.

					Sinc	le Ou	tput					ı	Dua	l Outp	ut †
Full Size	1.5V	1.8V	2.5V	3.3V	5V	6V	7.5V	9V	12V	15V	28V		5V	12V	15V
	(1R5S)	(1R8S)	(2R5S)	(3R3S)	(05S)	(06S)	(7R5S)	(098)	(12 <b>S</b> )	(15S)	(28\$)		(05D)	(12D)	(15D)
MQFL-28															
16-40Vin Cont.	40A	40A	40A	30A	24A	20A	16A	13A	10A	8A	4A		24A	10A	8A
16-50Vin 1s Trans.*		1071		3011		2071	10/1	10/1	10/1	0			Total	Total	Total
Absolute Max Vin = 60V												ļ			
MQFL-28E															
16-70Vin Cont. 16-80Vin 1s Trans.*	40A	40A	40A	30A	24A	20A	16A	13A	10A	8A	4A		24A Total	10A Total	8A Total
Absolute Max Vin =100V													iotai	iotai	iotai
MOFL-28V															
16-40Vin Cont.															
5.5-50Vin 1s Trans.*	40A	40A	40A	30A	20A	17A	13A	11A	8A	6.5A	3.3A				
Absolute Max Vin = 60V															
MQFL-28VE												ĺ			
16-70Vin Cont.	40A	40A	40A	30A	20A	17A	13A	11A	8A	6.5A	3.3A				
5.5-80Vin 1s Trans.*	104	10/4	104	307	207	1//	15/4	117	0.4	0.5A	3.34				
Absolute Max Vin = 100V															
MQFL-270				\				1							
155-400Vin Cont.	40A	40A	40A	30A	24A	20A	16A	13A	10A	8A	4A		24A Total	10A Total	8A Total
155-475Vin 1s Trans.*  Absolute Max Vin = 550V													iotai	IOtal	iotai
MQFL-270L														٠.	
65-350Vin Cont.	40A	40A	30A	22A	15A	12A	10A	8A	6A	5A	2.7A		15A Total	6A Total	5A Total
65-475Vin 1s Trans.*													iotai	lotai	iotai
Absolute Max Vin = 550V					Cinc	la Ow	t and the						Dur	I Oute	
	1.5V	1.8V	2.5V	3.3V	5V	le Ou	7.5V	9V	12V	15V	28V		Dua 5V	l Outp	15V
Half Size	(1R5S)	(1R8S)	(2R5S)	(3R3S)	(05S)	(06S)	(7R5S)	(09S)	(12S)	(15 <b>S</b> )	(28S)		(05D)	(12D)	(15D)
MQHL-28	(TKJ3)	(TKU3)	(2K33)	(3K33)	(033)	(003)	(7 KJ3)	(033)	(123)	(133)	(203)		(03D)	(IZD)	(13D)
16-40Vin Cont.													10A	4A	3.3A
16-50Vin 1s Trans.*	20A	20A	20A	15A	10A	8A	6.6A	5.5A	4A	3.3A	1.8A		Total	Total	Total
Absolute Max Vin = 60V															
MQHL-28E															
16-70Vin Cont.	20A	20A	20A	15A	10A	8A	6.6A	5.5A	4A	3.3A	1.8A		10A	4A	3.3A
16-80Vin 1s Trans.*				2371	23/1	<i>57</i> (	0.071	3.571	.,,	3.57			Total	Total	Total
Absolute Max Vin =100V															
MQHR-28															
16-40Vin Cont. 16-50Vin 1s Trans.*	10A	10A	10A	7.5A	5A	4A	3.3A	2.75A	2A	1.65A	0.9A		5A Total	2A Total	1.65A Total
Absolute Max Vin = 60V													10(01	10(0)	iotai
MQHR-28E															
16-70Vin Cont.														٥.	
	10A	10A	10A	7.5A	5A	4A	3.3A	2.75A	2A	1.65A	0.9A		5A Total	2A Total	1.65A Total
16-80Vin 1s Trans.*													iotai	10(0)	iotai
Absolute Max Vin = 100V															

Check with factory for availability.

<sup>†80%</sup> of total output current available on any one output.
\*Converters may be operated at the highest transient input voltage, but some component electrical and thermal stresses would be beyond MIL-HDBK-1547A guidelines.

Output: ±5V

**Current: 5A Total** 

### **PART NUMBERING SYSTEM**

The part numbering system for SynQor's MilQor DC-DC converters follows the format shown in the table below.

Not all combinations make valid part numbers, please contact SynQor for availability. See the Product Summary web page for more options.

**Example: MQHR-28-05D-Y-ES** 

Model	Input Output Voltage(s)		Package Outline/	Screening	
Name	Voltage Range	Single Output	Dual Output	Pin Configuration	Grade
MQFL MQHL MQHR	28 28E 28V 28VE 270 270L	1R5S 1R8S 2R5S 3R3S 05S 06S 7R5S 09S 12S 15S 28S	05D 12D 15D	U X Y W Z	C ES HB

### **APPLICATION NOTES**

A variety of application notes and technical white papers can be downloaded in pdf format from the SynQor website.

#### Contact SynQor for further information and to order:

Phone: 978-849-0600 Toll Free: 1-888-567-9596 Fax: 978-849-0602

E-mail: mqnbofae@synqor.com

Web: www.synqor.com
Address: 155 Swanson Road

Boxborough, MA 01719

**USA** 

#### **PATENTS**

SynQor holds numerous U.S. patents, one or more of which apply to most of its power converter products. Any that apply to the product(s) listed in this document are identified by markings on the product(s) or on internal components of the product(s) in accordance with U.S. patent laws. SynQor's patents include the following:

 5,999,417
 6,222,742
 6,545,890
 6,594,159
 6,731,520
 6,894,68

 6,896,526
 6,927,987
 7,050,309
 7,072,190
 7,085,146
 7,119,524

 7,269,034
 7,272,021
 7,272,023
 7,558,083
 7,564,702
 7,765,687

 7,87,261
 8,023,290
 8,149,597
 8,493,751
 8,644,027
 9,143,042

#### Warranty

SynQor offers a two (2) year limited warranty. Complete warranty information is listed on our website or is available upon request from SynQor.